

# Vincent's CS70 Discussion 13A Notes

April 20, 2016

## 1 Markov Chains!

### 1.1 Some definitions

Before we define what a Markov chain is, we first need to define stochastic matrices.

**Definition 1.** An  $n \times n$  right stochastic matrix  $P$  is a square matrix that satisfies the following:

1.  $P(i, j) \geq 0 \quad \forall i, j \in \{1, 2, \dots, n\}$
2.  $\forall i \in \{1, 2, \dots, n\}, \quad \sum_{j=1}^n P(i, j) = 1.$

In other words, a right stochastic matrix is a square matrix with non-negative entries and row-sum equal to 1 for each row. We are now able to state the definition of a Markov chain.

**Definition 2.** A (finite) Markov chain  $M$  is a 4-tuple  $(\mathcal{X}, \pi_0, P, \{X_n\}_{n=0}^\infty)$  consisting of

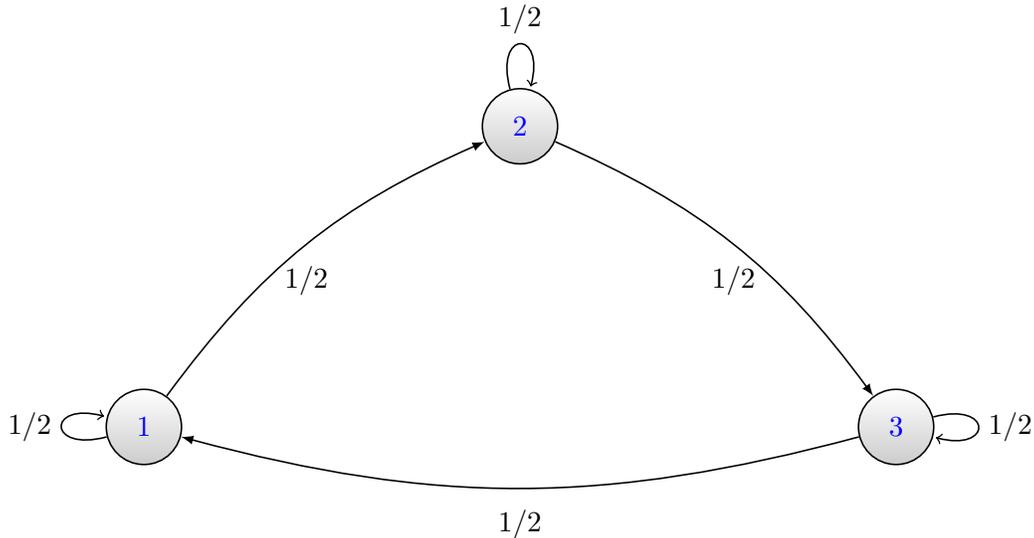
1. A finite set of states  $\mathcal{X} = \{1, 2, \dots, K\}$ .
2. A probability distribution  $\pi_0 : \mathcal{X} \rightarrow [0, 1]$  such that  $\sum_{i \in \mathcal{X}} \pi_0(i) = 1.$
3. A  $K \times K$  right stochastic matrix  $P.$
4. A sequence of random variables  $\{X_n\}_{n=0}^\infty$  satisfying
  - $\forall i \in \mathcal{X}, \quad \mathbb{P}(X_0 = i) = \pi_0(i)$
  - $\forall i, j \in \mathcal{X}, \quad \mathbb{P}(X_{n+1} = j | X_0, X_1, \dots, X_n = i) = P(i, j).$

There's quite a bit going on in this definition, so let's break it down to understand what's going on. Intuitively, a (finite) Markov chain represents a probabilistic walk through a given state space  $\mathcal{X}$ . At time  $t = 0$ , the probability that we find ourselves starting in state  $i \in \mathcal{X}$  is given by  $\pi_0(i)$ . Our stochastic matrix  $P$  encodes the probability of transitioning from state  $i$  to state  $j$  for  $i, j \in \mathcal{X}$ . In other words, given that we are at state  $i$  at time  $t = n$ , the probability that we move to state  $j$  at time  $t = n + 1$  is  $P(i, j)$ .

It is important to note that we “forget” about where we were at times  $t = 0, 1, \dots, n - 1$ : the probabilities of our next step only depend on the current state. Finally, the sequence  $\{X_n\}_{n=0}^\infty$

represents the possible locations we may be at any point in time. For example, the random variable  $X_0$  is our position at the start, and  $X_i$  denotes our position at time  $i$ . Of course, we have that  $\text{range}(X_i) \subseteq \mathcal{X}$  for  $i \in \mathbb{N}$ .

## 1.2 A simple example



Consider the Markov chain represented by the figure above, and suppose that our initial distribution is given by  $\pi_0(1) = 1$ ,  $\pi_0(2) = \pi_0(3) = 0$ . We have that  $\mathcal{X} = \{1, 2, 3\}$ , and finally

$$P = \begin{bmatrix} 0.5 & 0.5 & 0 \\ 0 & 0.5 & 0.5 \\ 0.5 & 0 & 0.5 \end{bmatrix}$$

Let's compute a few things using our example above. By our assumptions, we know that at time  $t = 0$ , we are guaranteed to start at state 1. Suppose we want to know the amount of time we expect to take to move from state 1 to state 3. Let's begin by denoting the expected amount of time to move from state  $i$  to state  $j$  by  $\beta(i, j)$ . Our goal is to compute  $\beta(1, 3)$ .

A bit of thought gives us that

$$\beta(1, 3) = 1 + \frac{1}{2}(\beta(1, 3) + \beta(2, 3))$$

Why? We have yet to reach our goal, so we are guaranteed to have to move at least once. Furthermore, with probability  $\frac{1}{2}$  we move to state 2 and from there expect to take  $\beta(2, 3)$  steps to move to state 3, or we stay in state 1 (also with probability  $\frac{1}{2}$ ) and from there expect to take  $\beta(1, 3)$  steps to get to state 3. Similarly, we see that

$$\beta(2, 3) = 1 + \frac{1}{2}(\beta(2, 3) + \beta(3, 3))$$

and

$$\beta(3, 3) = 0,$$

which we recognize as a system of three linear equations in three variables. Solving this system, we see that

$$\beta(1, 3) = 4$$

$$\beta(2, 3) = 2$$

$$\beta(3, 3) = 0,$$

so we expect 4 units of time to pass before moving from state 1 to state 3.

We conclude by noting that an alternate way of viewing this problem would be to simply view it as calculating the expectation of  $X = X_1 + X_2$ , where  $X_1, X_2 \sim \text{Geom}(\frac{1}{2})$ . This is because the only way to get from state 1 to state 3 is to first move to state 2, and also there is no way of going “backwards”. Thus, the expected number of steps to move from state 1 to 2 is 2, which is also the expected number of steps to move from state 2 to 3.